

**Hitachi Site
Yearly Performance Evaluation
Hitachi Airis II
2-Dec-07**

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MRI Equipment Evaluation Summary & Signature Page

Site Name: <u>Hitachi Site</u>	MRAP # <u>3235</u>
Address: _____	Survey Date: <u>12/2/07</u>
City, State, Zip _____	Report Date: <u>12/10/07</u>
MRI Mfg: <u>Hitachi</u>	Model: <u>Airis II</u>
	Field: <u>0.3</u>
MRI Scientist: <u>Moriel NessAiver, Ph.D.</u>	Signature: <u>Moriel NessAiver, Ph.D.</u>

Equipment Evaluation Tests

- | | Pass | Fail * | N/A |
|---|-------------------------------------|-------------------------------------|-------------------------------------|
| 1. Magnetic field homogeneity: | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 2. Slice position accuracy: | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 3. Table positioning reproducibility: | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 4. Slice thickness accuracy: | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 5. RF coils' performance: | | | |
| a. Volume QD Coils | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| b. Phase Array Coils | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| c. Surface Coils | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 6. Inter-slice RF interference (Crosstalk): | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 7. Soft Copy Display | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 8. Film Calibration | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |

Evaluation of Site's Technologist QC Program

- | | Pass | Fail * | N/A |
|--|--------------------------|--------------------------|-------------------------------------|
| 1. Set up and positioning accuracy: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 2. Center frequency: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 3. Transmitter attenuation or gain: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 4. Geometric accuracy measurements: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 5. Spatial resolution measurements: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 6. Low contrast detectability: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 7. Head Coil SNR (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 8. Body Coil SNR (weekly) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 9. Fast Spin Echo (FSE/TSE) ghosting levels: (daily) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 10. Film quality control: (weekly) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 11. Visual checklist: (weekly) | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |

*See comments page for description of any failures.

MRI Equipment Performance Evaluation Data Form

Site Name: Hitachi Site

Contact	Title	Phone	eMail
	Chief Tech		

Equipment Information

MRI Manufacturer: Hitachi Model: Airis II SN: C416 Software: V5.0R-3
 Camera Manufacturer: _____ Model: _____ SN: _____ Software: _____
 PACS Manufacturer: _____ Model: _____ SN: _____ Software: _____
 ACR Phantom Number used: 6998

1. Table Positioning Reproducibility:

Pass

Table motion out/in: _____

IsoCenter	Out/In	Out/In	Out/In
-4.6	-4.5	-5.2	

Measured Phantom Center

Comment: _____

2. Magnetic Field Homogeneity

See appendix A for field plots.

PASS

Last Year CF: N/A This Year CF: 12.65546 CF Change: NA

GRE TR/TE: 500/10 & 500/18 FOV: 300, BW 10 & 40 KHz

10 mm skip 10 mm, Flip Angle 45°, 256x256, 2nex

Comments: This shim is typical to poor.

	22 cm
Axial plane - Frequency L/R:	20-22
Axial plane - Frequency A/P:	22-26
Sagittal plane - Frequency H/F:	14-27

3. Slice Thickness Accuracy

FOV: 250mm Matrix: 256x256 (Slice #1 from ACR Phantom) All values in mm

Sequence	TR	TE	Flip	NSA	Calc	Target	% Error
SE (ACR)	500	20	90	1	5.48	5	9.6%
SE (Site T1)	500	18	90	1	5.49	5	9.8%
SE (20/80)	2000	20	90	1	5.59	5	11.8%
SE (20/80)	2000	80	90	2	5.02	5	0.4%
FSE(8)	4000	100	90	4	5.08	5	1.6%

Comments: _____

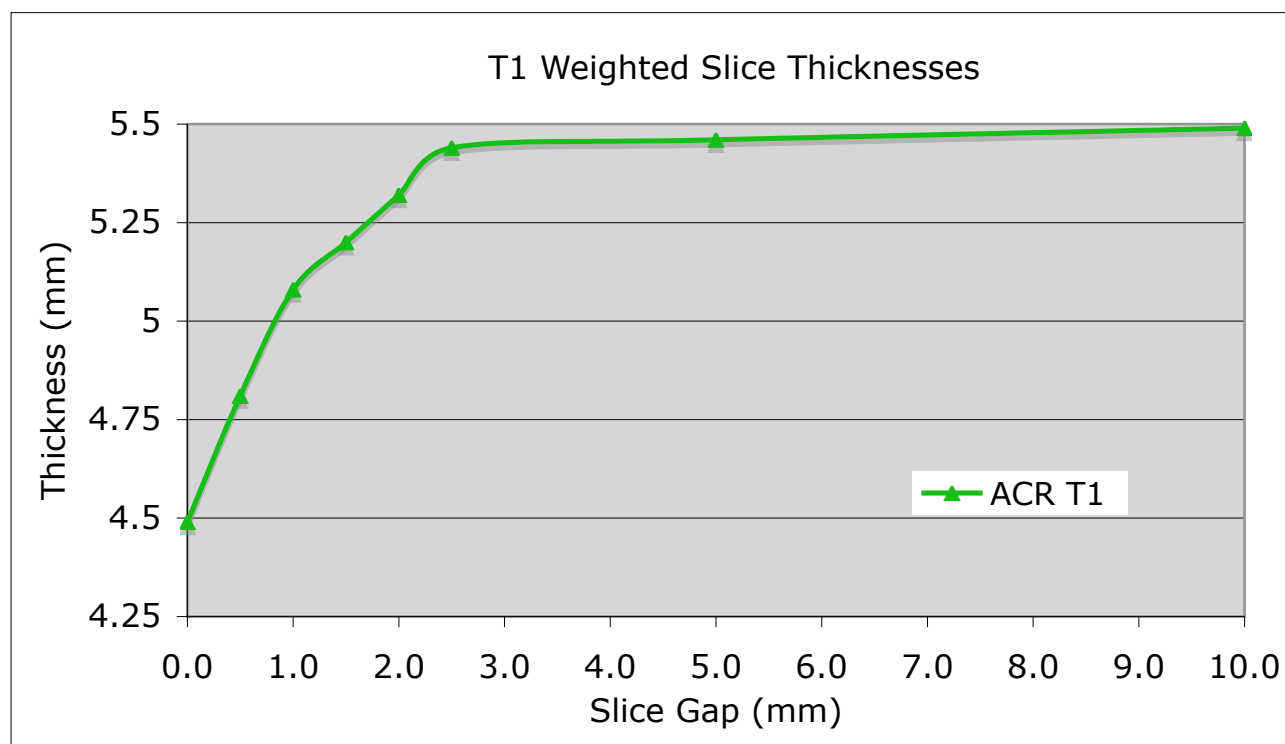
4. Slice Crosstalk (RF interference)

The following data were obtained using the ACR phantom slice thickness wedges to measure the slice profile of a typical T1 weighted sequences when the slice gap varies from 200% down to 0% (contiguous). As the slices get closer together it is expected that the edges of the slices will overlap causing a deterioration of the slice profile. The data shown below clearly demonstrates this effect. Once the slice gap drops below 40% of the slice thickness, the measured slice profile begins to drop. From this data it is clear that slice gaps should be at least 20% of the slice thickness and ideally should be greater than 40%.

All of the slice profiles can be seen in appendix B.

	Sequence Type	TR	TE	FOV (cm ²)	Matrix	NSA	Thickness	# of slices	Slice Measured
Site T1	SE	400	18	25	256x256	2	5	11	6

Skip	ACR T1
0.0	4.49
0.5	4.81
1.0	5.08
1.5	5.2
2.0	5.32
2.5	5.44
5.0	5.46
10.0	5.49



5. Soft & Hard Copy Displays

Luminance Meter Make/Model: Tektronix J16 Digital Photometer

Cal Expires: 4/6/07

Monitor Description: LCD display

Luminance Measured: Ft. lamberts

Measured Data					
Which Monitor	Center of Image Display	Top Left Corner	Top Right Corner	Bottom Left Corner	Bottom Right Corner
Console	32.4	29.8	27.8	30.8	29.3

Uniformity		
MAX	MIN	Percent Delta
32.4	27.8	15%

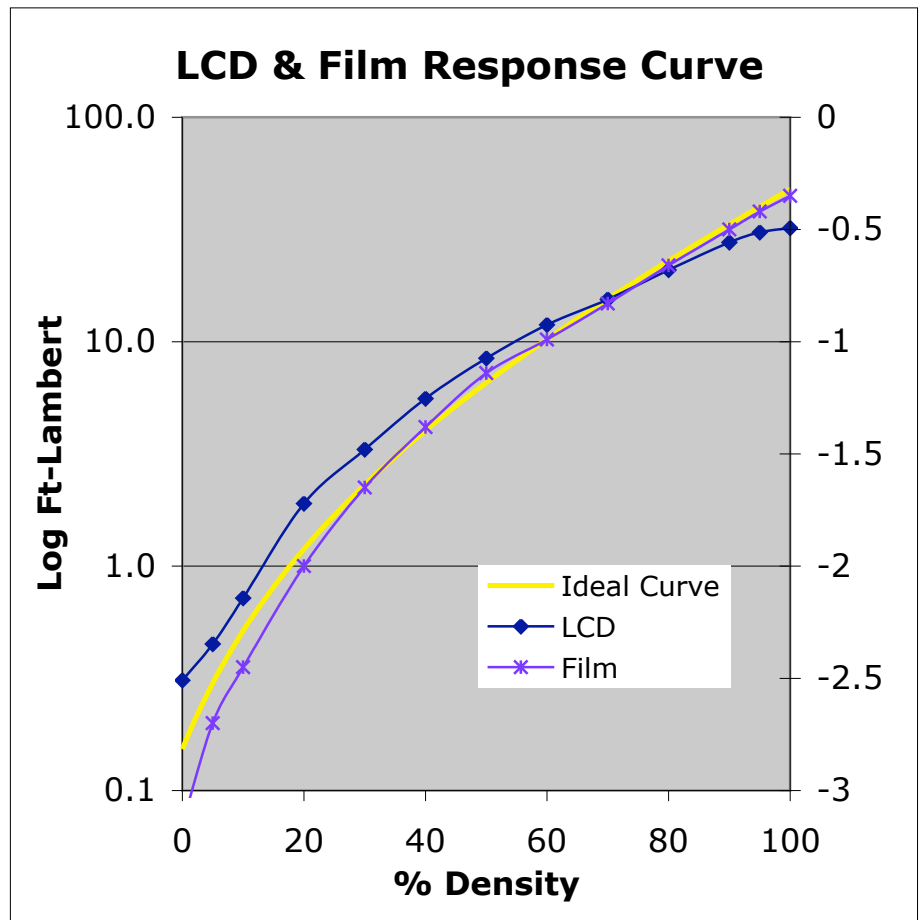
SMPTE
OK?
Y

$\% \text{ delta} = 200\% \times (\text{max} - \text{min}) / (\text{max} + \text{center})$ (>30% is action limit)

Minimum Brightness must be > 26.24 Ft. Lamberts

The display is adequate, the film printer is very good.

Density	Ft-Lambert	Film Density
0	0.31	-3.15
5	0.45	-2.7
10	0.72	-2.45
20	1.90	-2
30	3.31	-1.65
40	5.58	-1.38
50	8.44	-1.14
60	11.90	-0.99
70	15.5	-0.83
80	20.9	-0.66
90	27.7	-0.5
95	30.7	-0.42
100	32.1	-0.35



RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: MRQFC 53AN
 Revision: _____
 SN: KR18951804
 # of Channels 1

Coil: Body Flex Large

Mfg.: Hitachi

Mfg. Date: 3/3/1998 Coil ID: 1366

Phantom: Hitachi Bottle #4

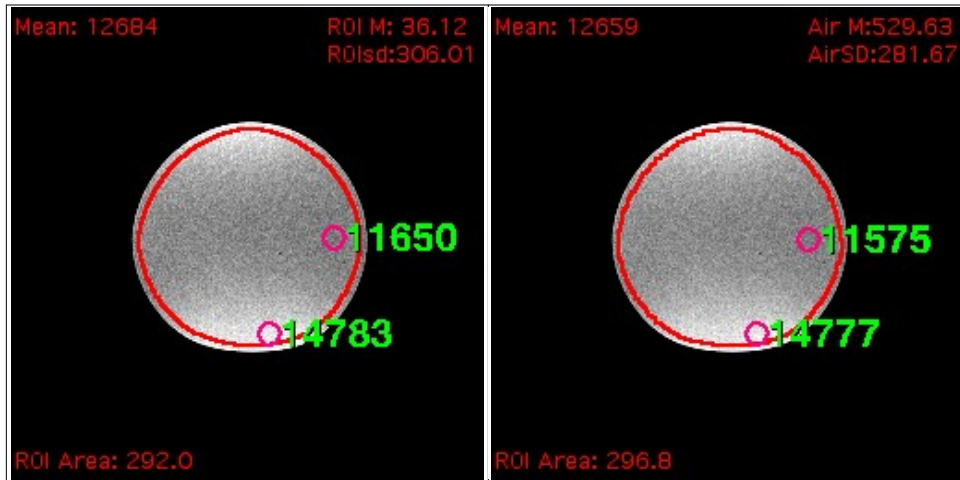
Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	42	256	256	24	1	5	-

Coil Mode: Body Flex L

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	12,684	14,783	11,650	36.1	306.01	NEMA	29.3	11.1	34.2	88.1%
A	12,659	14,777	11,575	529.6	281.67	Air	29.5	11.2	34.4	87.8%

The SNR of this coil is 12.5% lower than Florissant's



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: MRQFC 52AN
 Revision: _____
 SN: KR15159102
 # of Channels 1

Coil: Body Flex Medium

Mfg.: Hitachi

Mfg. Date: 6/14/2001 Coil ID: 1365

Phantom: Hitachi Bottle #4

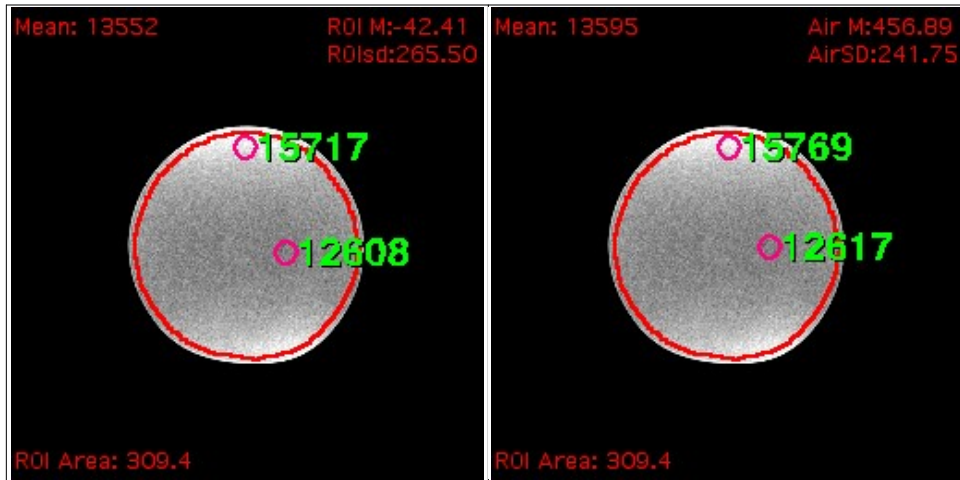
Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	42	256	256	24	1	5	-

Coil Mode: Body Flex M

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	13,552	15,717	12,608	-42.4	265.50	NEMA	36.1	13.7	41.9	89.0%
A	13,595	15,769	12,617	456.9	241.75	Air	36.9	14.0	42.7	88.9%

The SNR of this coil is 9% lower than Florissant's



Test Images

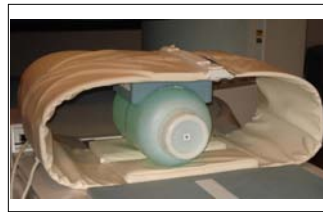
RF Coil Performance Evaluation

Coil: Body Flex X-Large

Mfg.: Hitachi

Mfg. Date: _____ Coil ID: 1368

Phantom: Hitachi Bottle #4



Test Date: 12/2/2007

Model: MR-QFC-55

Revision: _____

SN: _____

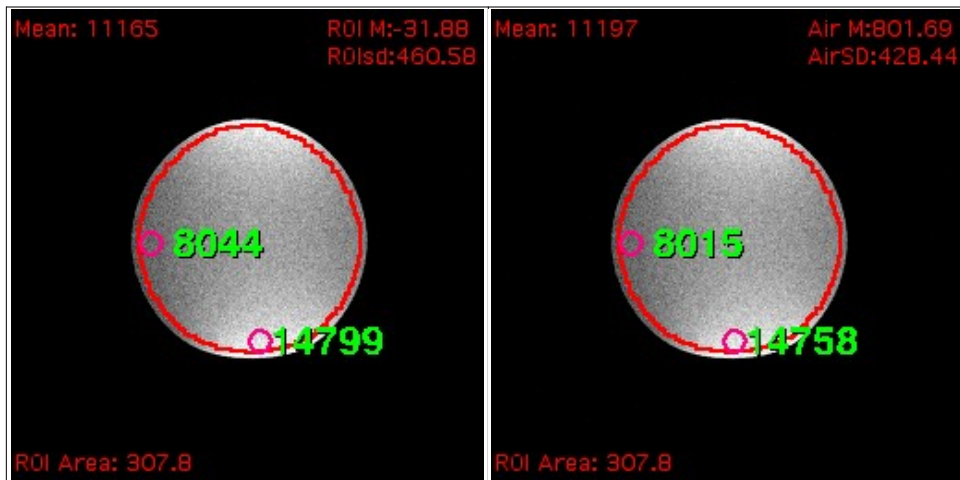
of Channels 1

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	42	256	256	24	1	5	-

Coil Mode: Body Flex XL

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	11,165	14,799	8,044	-32.0	461.00	NEMA	17.1	6.5	22.7	70.4%
A	11,197	14,758	8,015	802.0	428.00	Air	17.1	6.5	22.6	70.4%



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: 52AN
 Revision: _____
 SN: 938
 # of Channels 1

Coil: C-Spine Quad

Mfg.: Hitachi

Mfg. Date: 6/14/2001 Coil ID: 1364

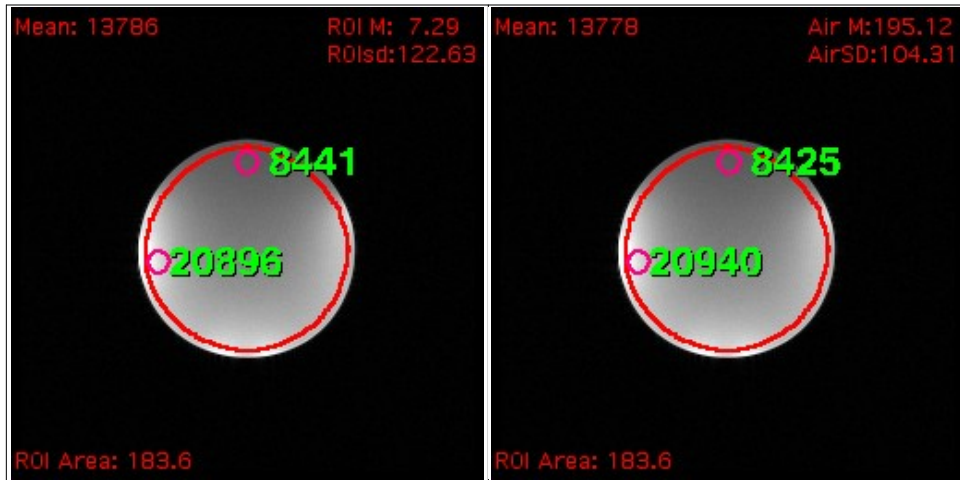
Phantom: Hitachi Bottle #3

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	36	256	256	24	1	5	-

Coil Mode: Quad Cspine

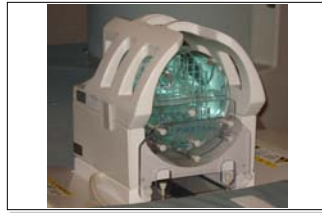
Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	13,786	20,896	8,441	7.3	122.63	NEMA	79.5	41.1	120.5	57.5%
A	13,778	20,940	8,425	195.0	104.30	Air	86.6	44.7	131.6	57.4%



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: _____
 Revision: _____
 SN: _____
 # of Channels 1

Coil: Head Coil

Mfg.: Hitachi

Mfg. Date: _____ Coil ID: 1363

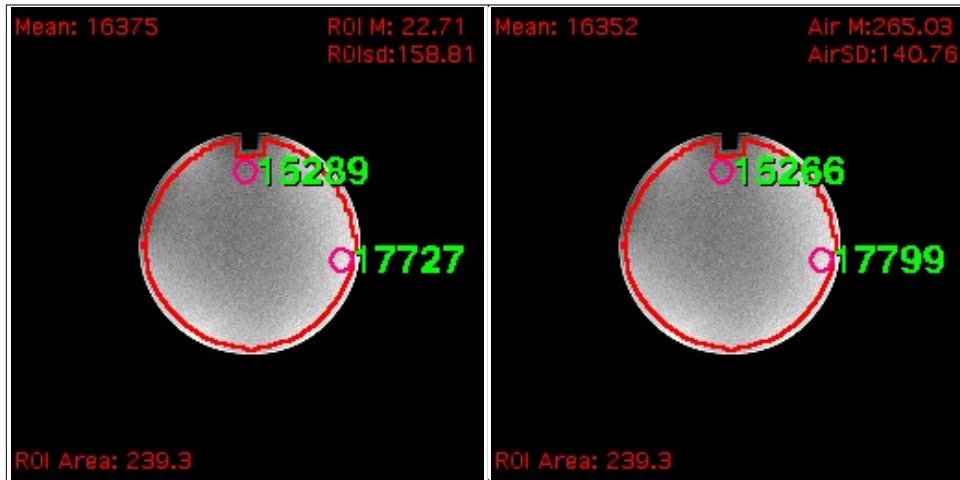
Phantom: ACR Phantom

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	40	256	256	24	1	5	-

Coil Mode: Head

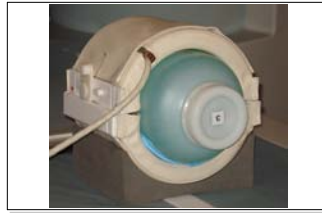
Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	16,375	17,727	15,289	22.7	158.81	NEMA	72.9	30.5	78.9	92.6%
A	16,352	17,799	15,266	265.0	140.76	Air	76.1	31.9	82.9	92.3%



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: MR-QKE 51
 Revision: _____
 SN: KR12403962
 # of Channels 1

Coil: Knee

Mfg.: Hitachi

Mfg. Date: 5/28/2001 Coil ID: 1367

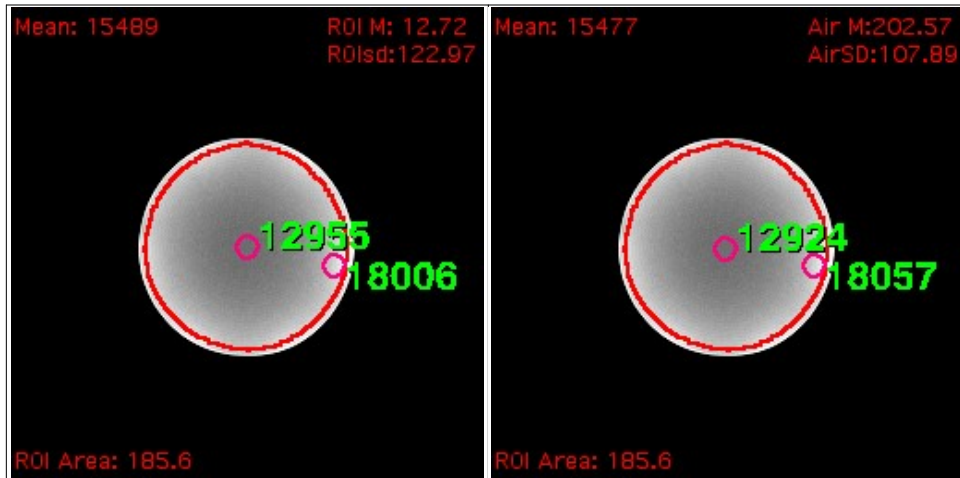
Phantom: Hitachi Bottle #3

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	36	256	256	24	1	5	-

Coil Mode: Knee

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	15,489	18,006	12,955	12.7	122.97	NEMA	89.1	46.0	103.6	83.7%
A	15,477	18,057	12,924	202.6	107.89	Air	94.0	48.6	109.7	83.4%



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: MR-JCL 52
 Revision: _____
 SN: KR15176102
 # of Channels 1

Coil: Latch/Joint(Oval)

Mfg.: Hitachi

Mfg. Date: 6/26/2001 Coil ID: 1370

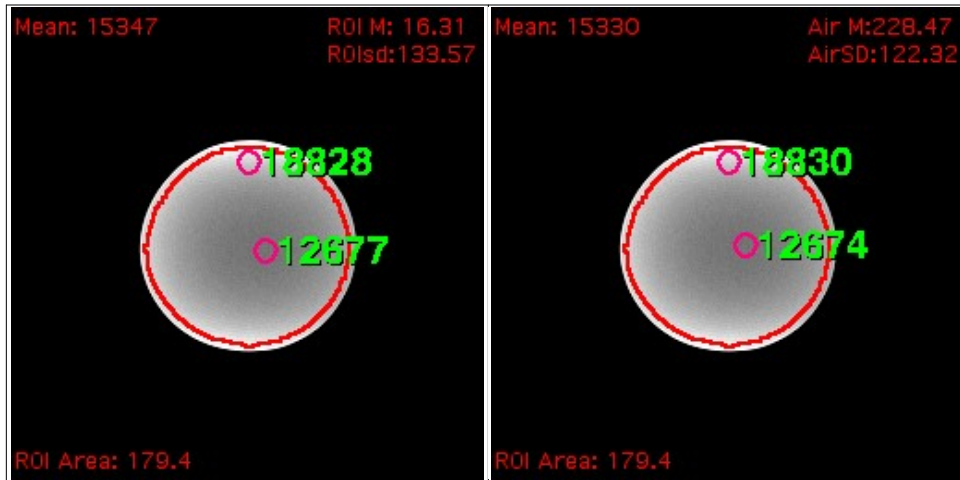
Phantom: Hitachi Bottle #3

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	36	256	256	24	1	5	-

Coil Mode: Latch/Joint

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	15,347	18,828	12,677	16.3	133.57	NEMA	81.3	42.0	99.7	80.5%
A	15,330	18,830	12,674	228.5	122.32	Air	82.1	42.4	100.9	80.5%



Test Images

RF Coil Performance Evaluation



Test Date: 12/2/2007
 Model: MR-JC 53
 Revision: _____
 SN: KR15157101
 # of Channels 1

Coil: Neck/Joint (round)

Mfg.: Hitachi

Mfg. Date: 6-21-2001 Coil ID: 1369

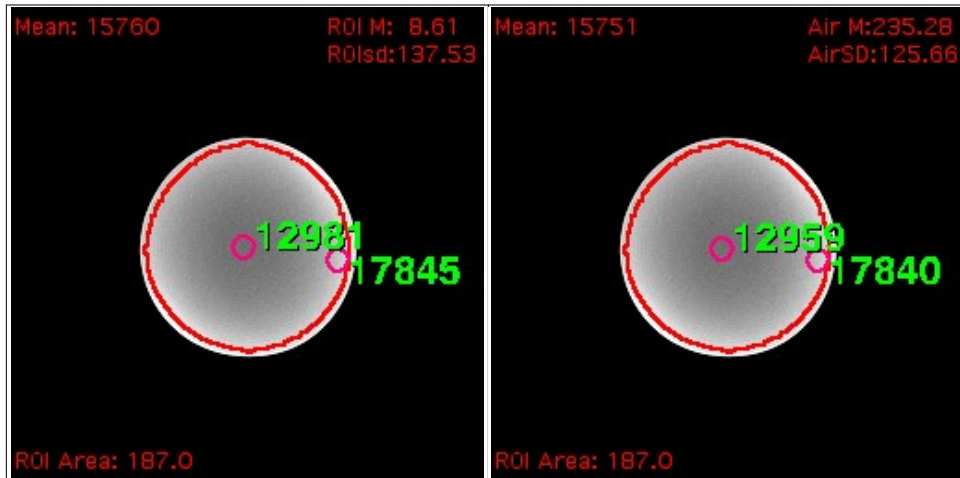
Phantom: Hitachi Bottle #3

Sequence	TR	TE	Plane	FOV	Nx	Ny	BW	NSA	Thickness	Gap
SE	300	20	T	36	256	256	24	1	5	-

Coil Mode: Neck/Joint

Analysis of Test Image

Measured Data							Calculated Results			
Label	Mean	Max	Min	Back ground	Noise SD	Noise Type	Mean SNR	Normal-ized	Max SNR	Uni-formity
N	15,760	17,845	12,981	8.6	137.53	NEMA	81.0	41.9	91.8	84.2%
A	15,751	17,840	12,959	235.3	125.66	Air	82.1	42.5	93.0	84.2%



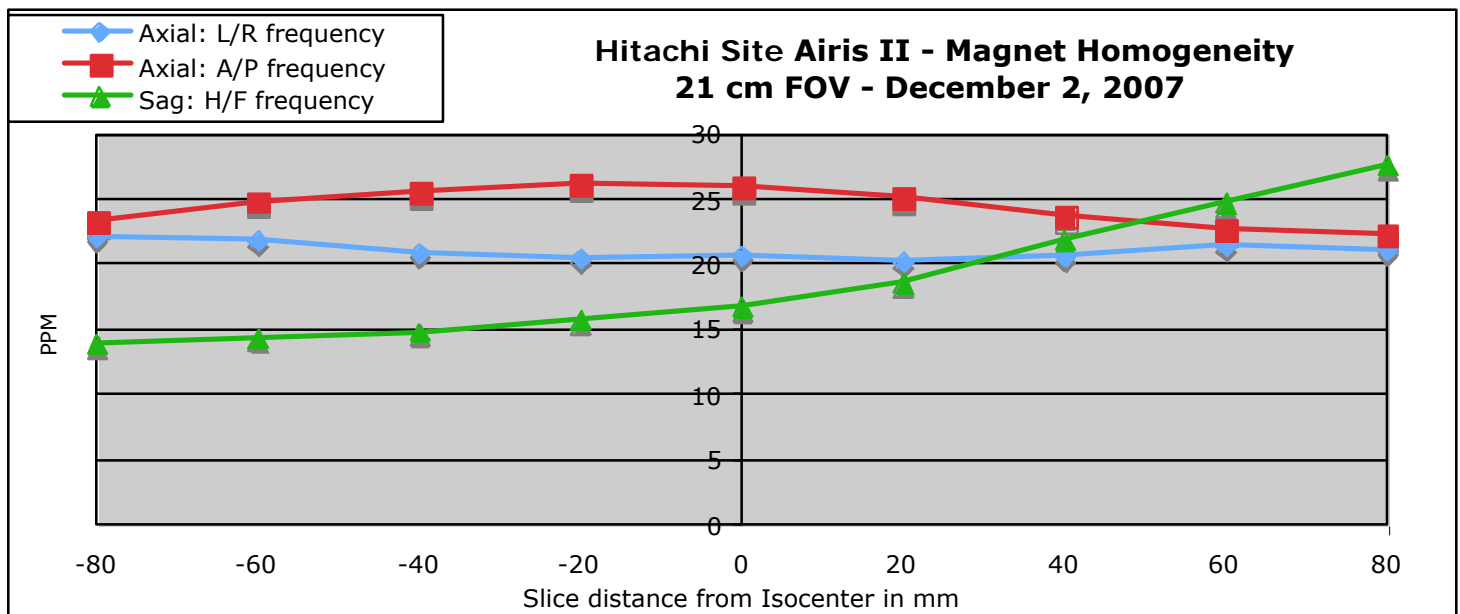
Test Images

Appendix A: Estimating Homogeneity by Measuring Geometric Distortion

The preferred method of measuring magnet homogeneity is to use gradient echo imaging sequence to obtain phase images also known as phase maps. Ideally, if a magnet is absolutely perfectly uniform then all of the protons will be perfectly in-phase with each other at the echo time. Any variations in the magnetic field will cause variations in the resonance frequencies across the field of view (FOV) which, in turn, will cause variations in the signal phase that are directly proportional to the variations in the magnet homogeneity. In order to obtain these phase map images, it is necessary to be able to reconstruct phase images instead of the usual magnitude images. Unfortunately, Hitachi does not provide that option on their scanners except to the service engineers and I was unable to obtain the assistance of the site engineer to make this measurement.

Fortunately, there is an alternative, although not a good one. When acquiring images, one encodes the spatial location of signal by applying a readout gradient of known strength, for example 1000 Hz/cm. When the images are reconstructed, the signal is analyzed for the strength of the signal at different frequencies and they are then mapped to the different pixels in the image. The assumption is that the ONLY thing that affects the signal frequency is the imaging or readout gradient. If there are inhomogeneities in the magnetic field, this will cause spatially varying frequencies unrelated to the readout gradient which will, in turn, cause errors in mapping the signal to different pixels which will be visible as geometric distortion. By imaging a phantom using two different receiver bandwidths (BW) it is possible to estimate the variations in the magnetic field at the edges of the phantom by measuring the differences in the distortion of the two sets of images.

The following pages depict the results of imaging the largest Hitachi bottle phantom (#4) which has an approximate diameter just over 21 cm, using a 39 Hz/pixel and a 156 Hz/pixel gradient. This was done in the axial plane with the readout gradient in both the L/R and A/P directions and in the sagittal plane with H/F readout gradient. Nine slices were acquired with each set using a 10 mm thick slice with a 10 mm gap. The phantom edges were detected and a set of radial lines were drawn with radial lengths measured as a function of rotational angle. The difference in radial diameters for the two sets of gradients were calculated and then converted to differences in frequencies (in Hz.) These values were then divided by the magnets operating frequency, 12.7MHz to provide a value in Parts per Million (PPM). Below is a graph of the measured PPM for the three different gradient directions. Although I have very little experience with these type of results on a low field magnet, I believe these data are somewhere between typical and poor. The values in the graph below are about 50-75% higher than Florissant



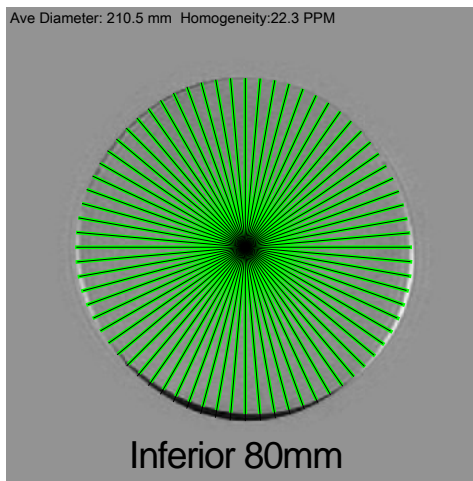
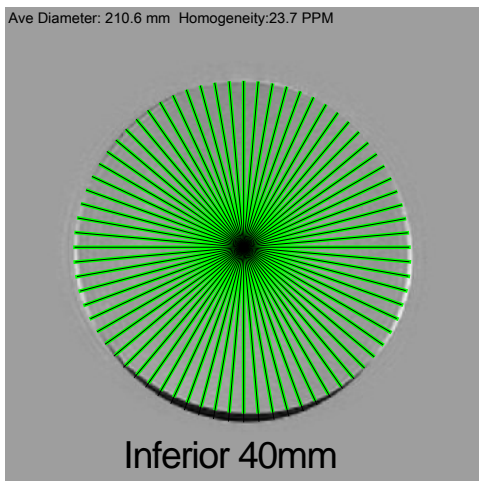
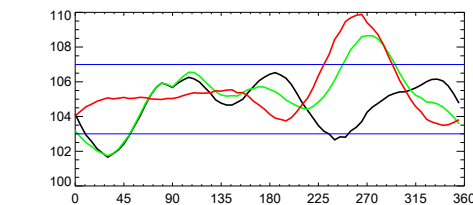
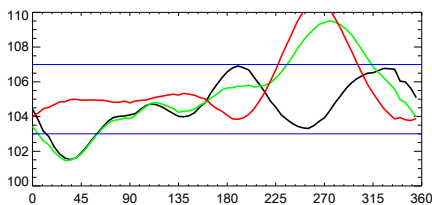
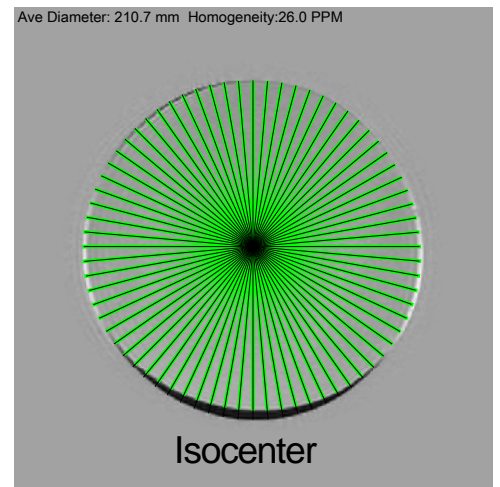
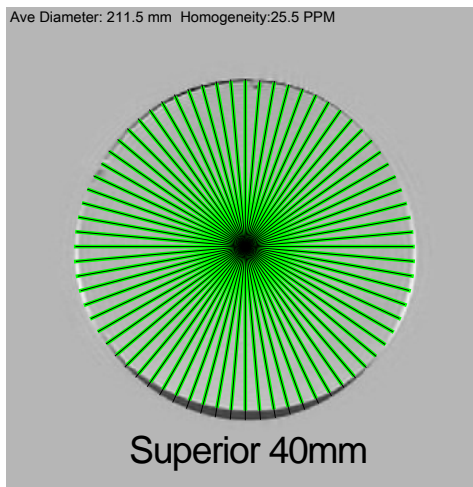
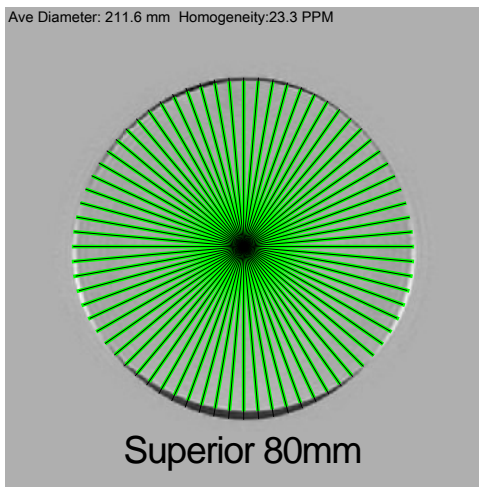
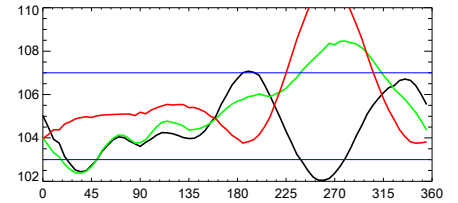
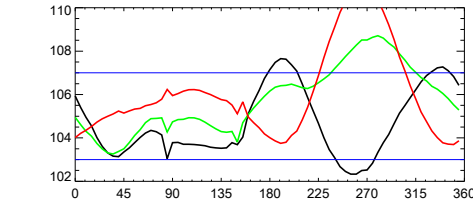
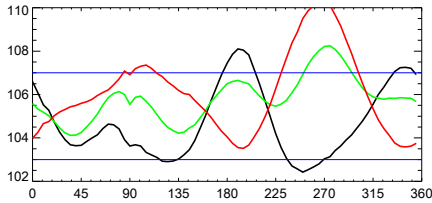
Appendix A: Estimating Homogeneity by Measuring Geometric Distortion Axial Plane - Frequency Direction: Anterior to Posterior Measured December 2, 2007

The green lines are radii acquired with 156 Hz/pixel (least distortion)

The black lines are radii acquired with 39 Hz/pixel (most distortion)

The red plots are the differences in the radii.

The images are the subtraction of the images using the two BW values



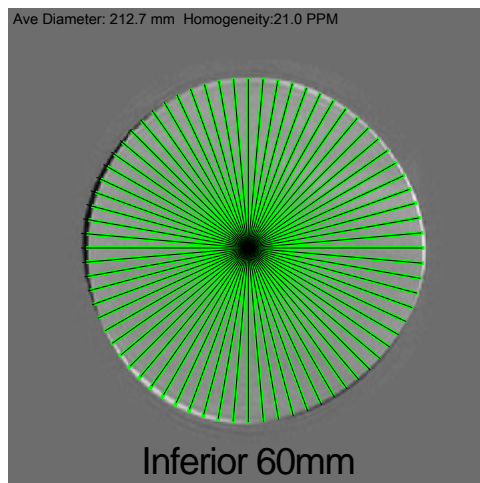
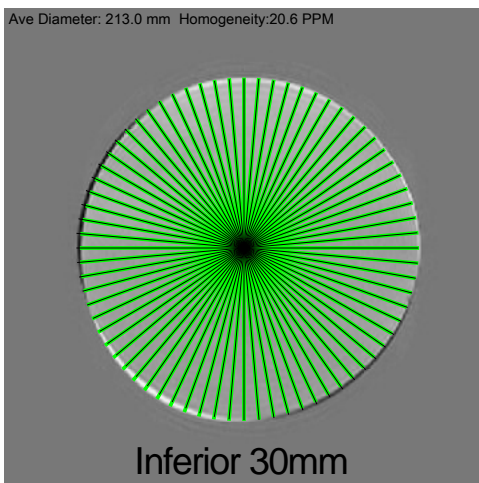
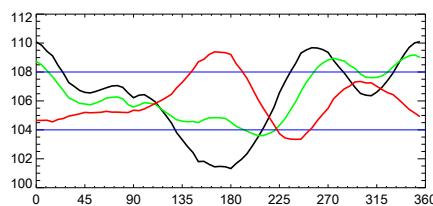
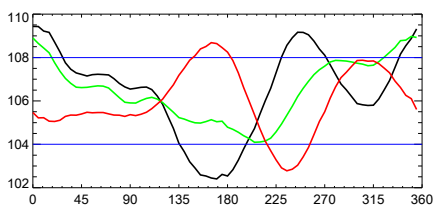
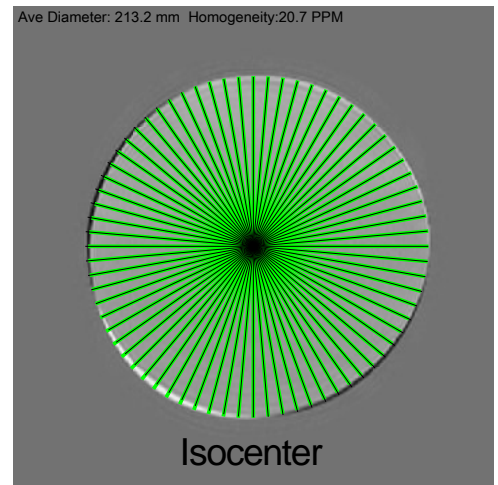
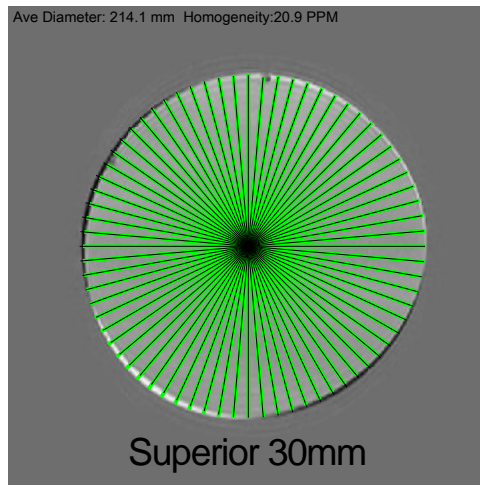
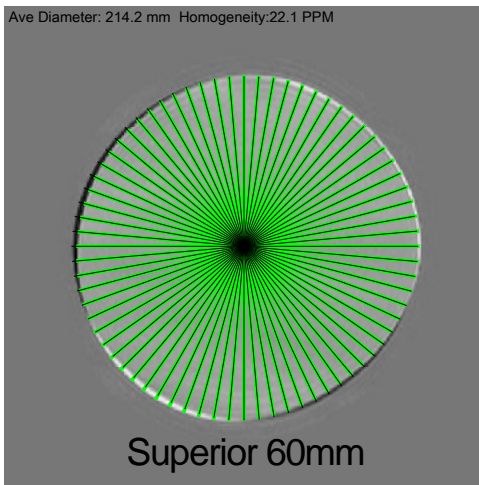
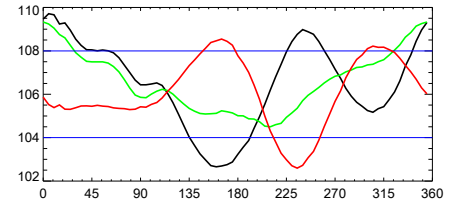
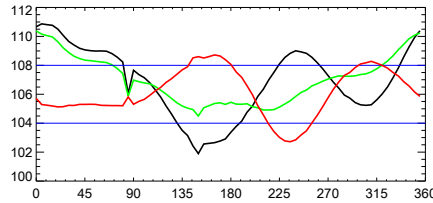
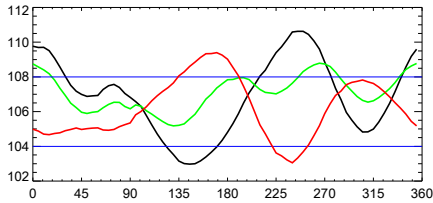
Appendix A: Estimating Homogeneity by Measuring Geometric Distortion Axial Plane - Frequency Direction: Left to Right Measured December 2, 2007

The green lines are radii acquired with 156 Hz/pixel (least distortion)

The black lines are radii acquired with 39 Hz/pixel (most distortion)

The red plots are the differences in the radii.

The images are the subtraction of the images using the two BW values



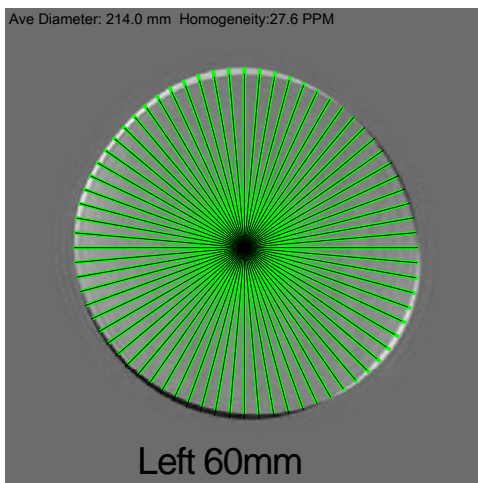
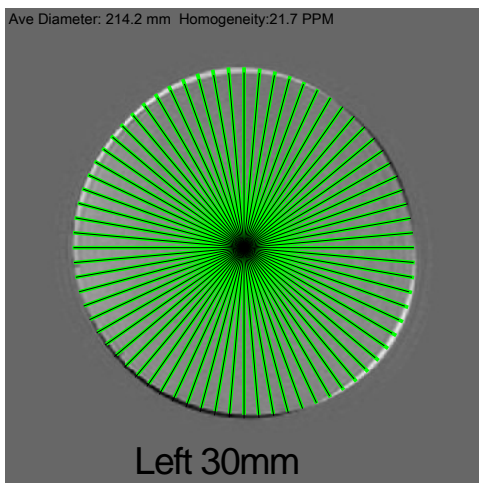
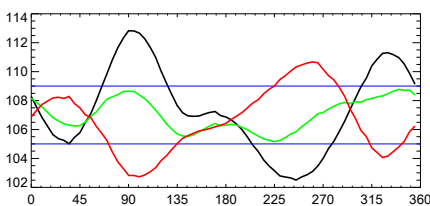
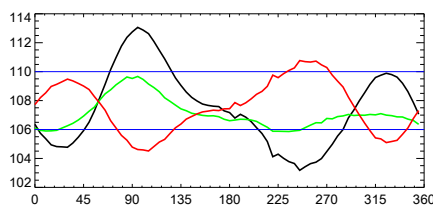
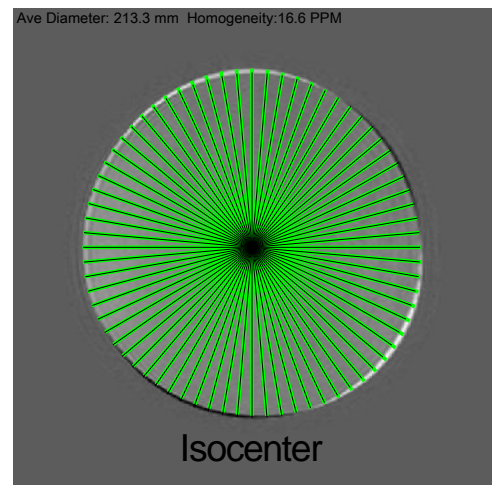
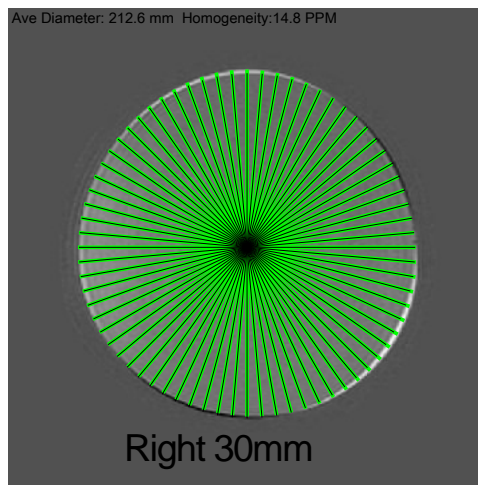
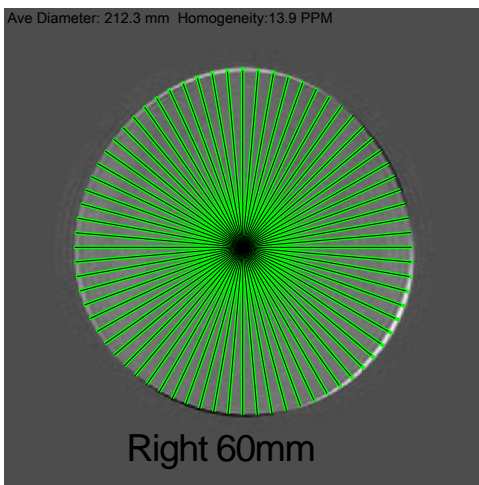
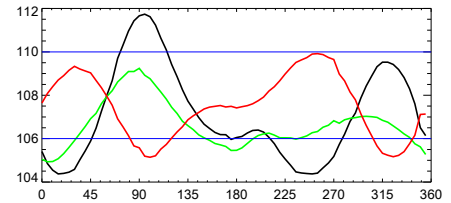
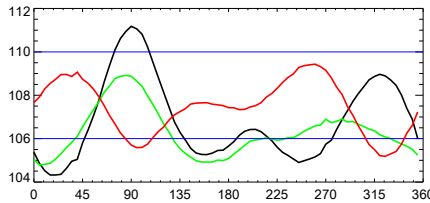
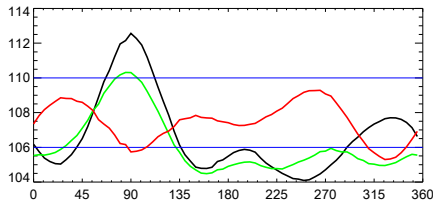
Appendix A: Estimating Homogeneity by Measuring Geometric Distortion Sagittal Plane - Frequency Direction: Head to Foot Measured December 2, 2007

The green lines are radii acquired with 156 Hz/pixel (least distortion)

The black lines are radii acquired with 39 Hz/pixel (most distortion)

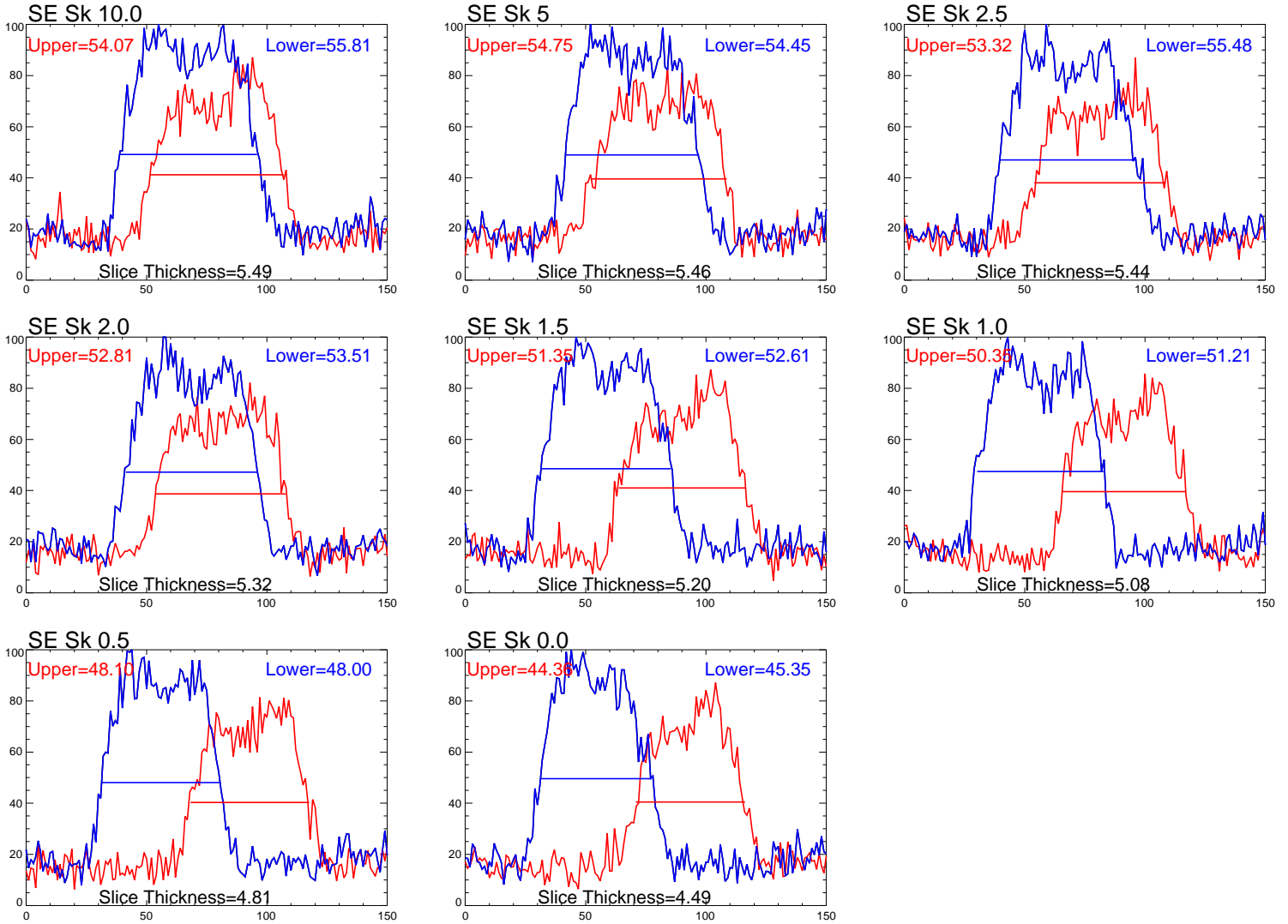
The red plots are the differences in the radii.

The images are the subtraction of the images using the two BW values

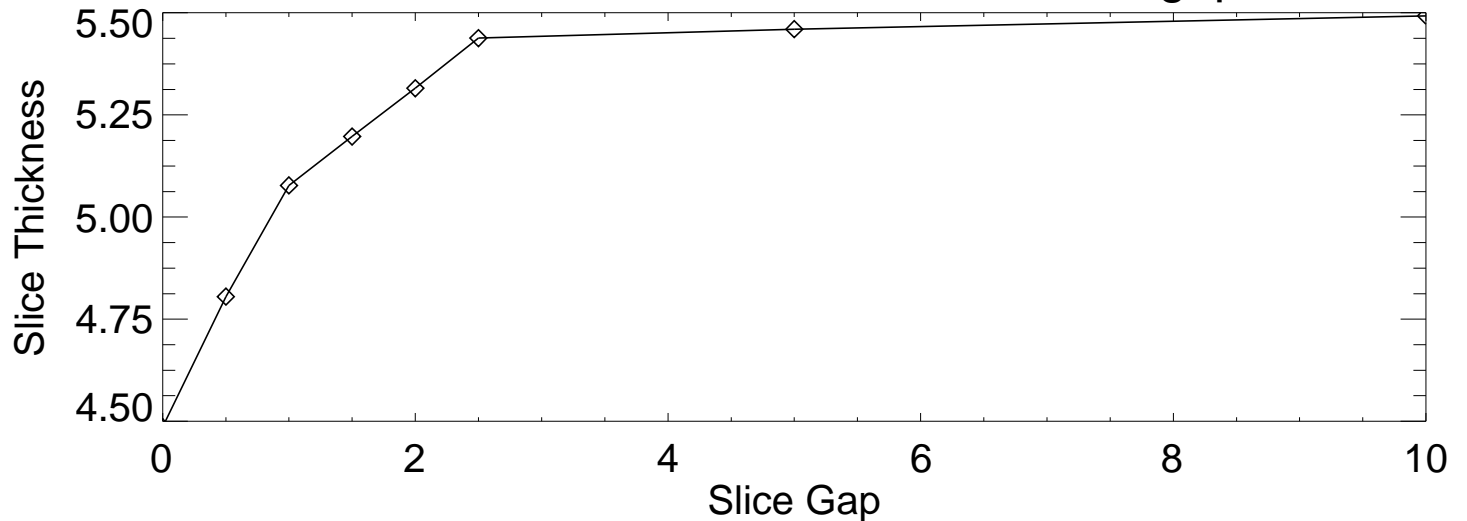


Appendix B: RF Slice Profiles and Crosstalk

Spin Echo : ACR T1
 TR/TE = 400/18
 BW = 20 KHz
 nex = 2
 Scan time: 3:25



Slice thickness as a function of slice gap



Coil Used: Head Coil

Test Date: 12/2/2007

Sagittal Locator							
1	Length of phantom, end to end (mn 148±2)	145.8	= calculated field				
		(SE 500/20)	(SE 2000/20)	(SE 2000/80)	(Site T1)	(Site T2)	
Slice Location #1		ACR T1	ACR PD	ACR T2	Site T1	Site T2	
2	Resolution ••••	0.9	0.9	0.9	1.0	1.0	
3	(1.10, 1.00, 0.90 mm) •	1.0	1.0	0.9	1.0	1.0	
4	Slice Thickness Top	56.3	57.2	49.9	55.3	50.1	
5	(fwhm in mm) Bottom	53.4	54.6	50.5	54.5	51.5	
6	Calculated value 5.0±0.7	5.48	5.59	5.02	5.49	5.08	
7	Wedge (mm) ■ = + ■ = -	-1.1	-3.4	-3.7	-1.2	-1.7	
8	Diameter (mm) (190±2) ⊕	191.2	190.6	191.8	190.6	190.2	
9		⊖	189.1	189.2	189.0	189.1	189.3
Slice Location #5							
10	Diameter (mm) (190±2) ⊕	191.5	190.7	192.7	190.6	190.2	
11		⊖	189.0	189.1	188.8	189.0	189.0
12		⊗	189.2	189.1	190.2	189.0	188.9
13		⊙	188.1	187.8	188.2	189.0	187.5
Slice Location #7							
14	Signal Big ROI	11167	11929	6840	22766	21642	
15	(mean only) High	12398	13051	7829	24804	24227	
16	Low	10112	10826	6026	20868	17978	
17	Uniformity (>87.5%)	89.8%	90.7%	87.0%	91.4%	85.2%	
18	Background Noise Top	296.2 ±161.8	338.2 ±179.13	217.7 ± 117.1	479.2 ± 258.5	591.1 ±292.78	
19	Bottom	312.6 ±165.6	340.4 ±181.35	231.9 ±125.38	487.6 ±264.88	591.1 ±308.19	
20	(mean ±std dev) Left	314.2 ±167.7	347 ±183.85	264.8 ±135.98	527.4 ±287.47	789.9 ±424.56	
21	Right	313.5 ±166.4	404.1 ±203.54	271.4 ±135.52	528.2 ±273.90	912.1 ±429.41	
22	Ghosting Ratio (<2.5%)	0.1%	0.3%	0.6%	0.2%	1.2%	
23	SNR (no spec)	68	66	56	87	72	
Low Con Detectability							
24	Slice Location #8 1.4%	0	0	0	1	0	
25	Slice Location #9 2.5%	2	0	0	2	1	
26	Slice Location #10 3.6%	5	2	1	7	3	
27	Slice Location #11 5.1%	6	7	8	8	8	
28	Total # of Spokes (>=9)	13	9	9	18	12	
Slice Location #11							
29	Wedge (mm) ■ = + ■ = -	-1.5	-3.2	-3.2	-1.3	-1.9	
30	Slice Position Error	-0.4	0.1	0.4	-0.1	-0.2	

Sequence parameters

Test Date: 12/2/2007

Coil Used: Head Coil

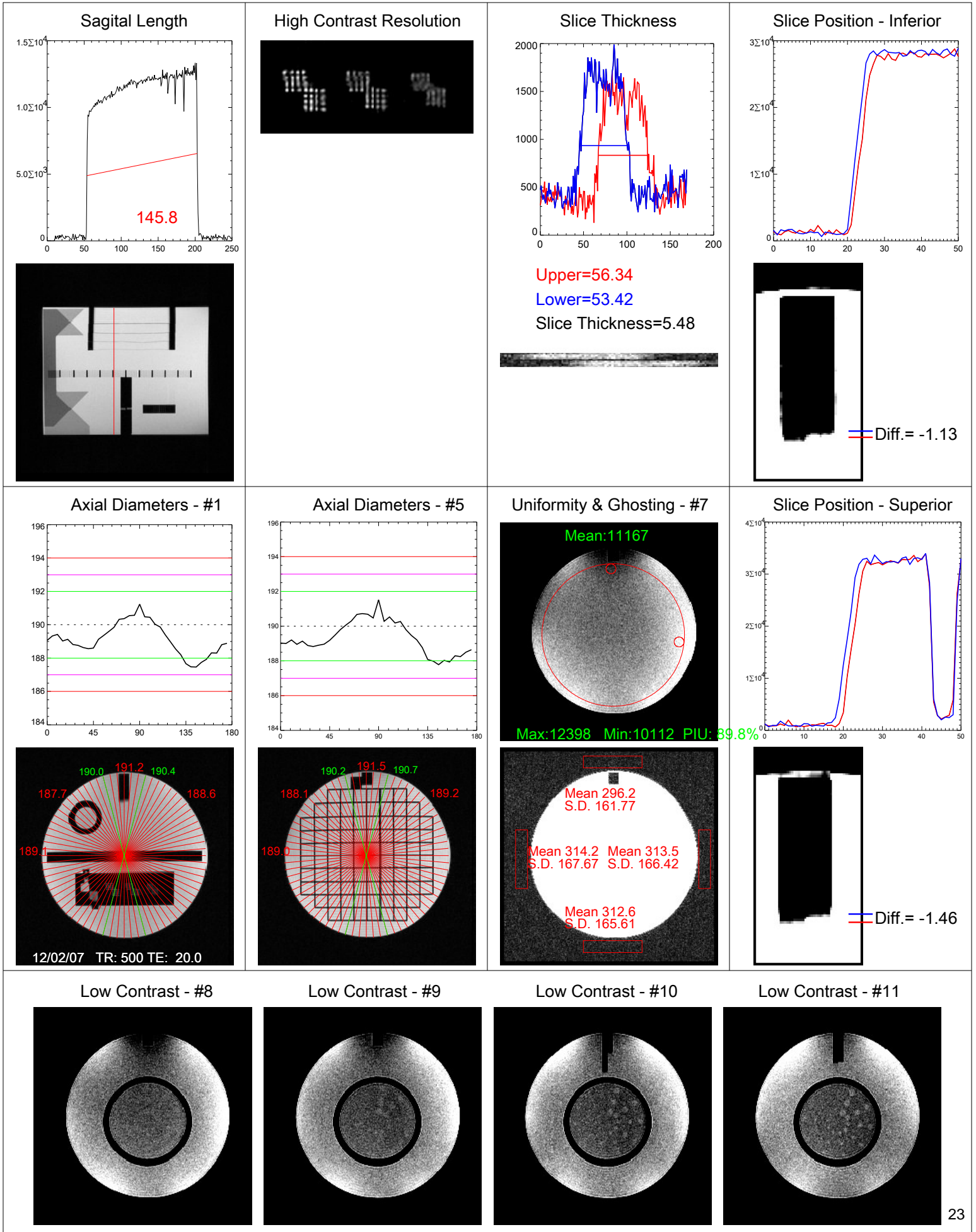
Test ID 228

Study Description	Pulse Sequence (ETL)	TR (ms)	TE (ms)	FOV (cm)	Phase Sample Ratio	Number of Slices	Thickness (mm)	Slice Gap	NSA (Nex)	Freq Matrix	Phase Matrix	Band Width (kHz)	Scan Time (min:sec)
ACR T1	SE	500	20	25	1	11	5	5	1	256	256	16	2:09
ACR PD	Dual Echo SE	2000	20	25	1	11	5	5	1	256	256	18	8:32
ACR T2	Dual Echo SE	2000	80	25	1	11	5	5	1	256	256	8	8:32
Site T1	SE	500	18	25	1	11	5	5	2	256	256	20	3:44
Site T2	FSE(8)	4000	100	25	1	11	5	5	4	256	256	22.7	7:28

Magnet ID: 180

Coil ID: 1363

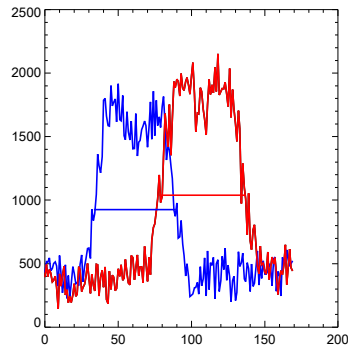
TestID: 228



High Contrast Resolution



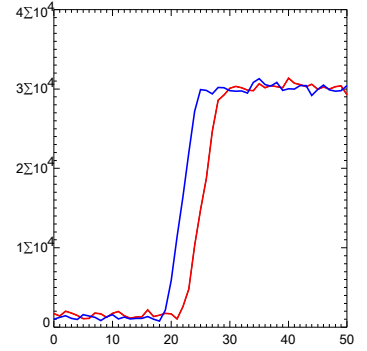
Slice Thickness



Upper=57.17
Lower=54.62
Slice Thickness=5.59

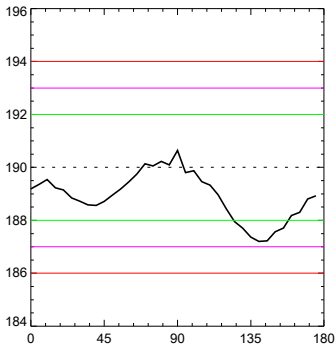


Slice Position - Inferior

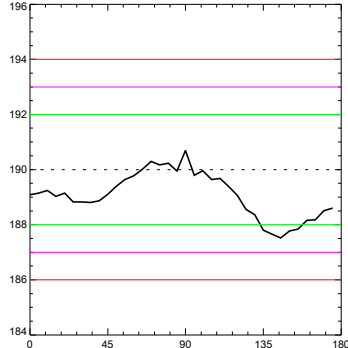


Diff. = -3.35

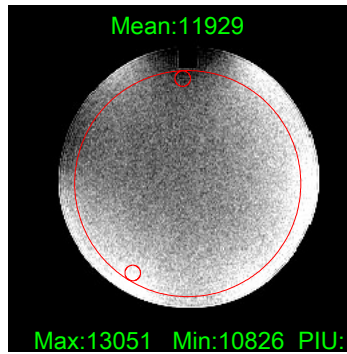
Axial Diameters - #1



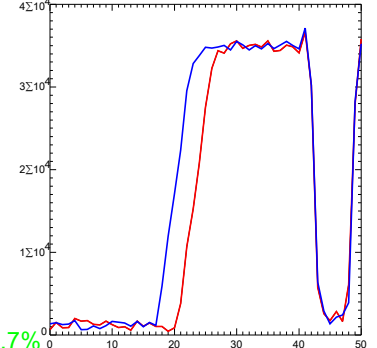
Axial Diameters - #5



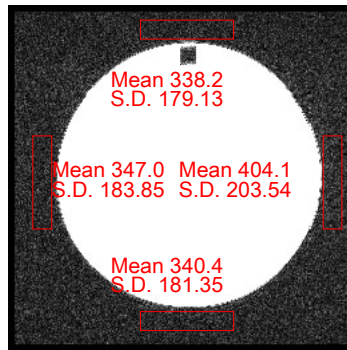
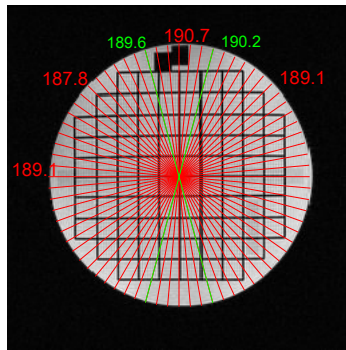
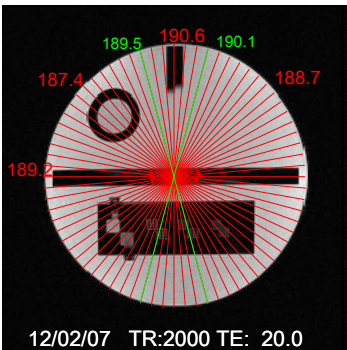
Uniformity & Ghosting - #7



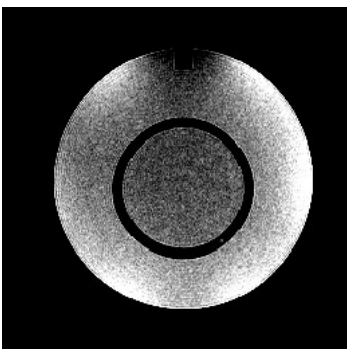
Slice Position - Superior



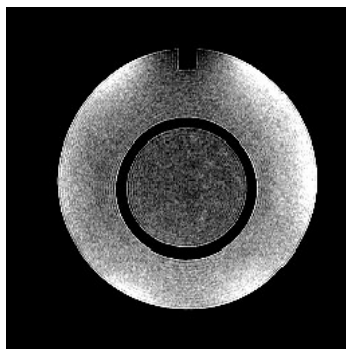
Diff. = -3.21



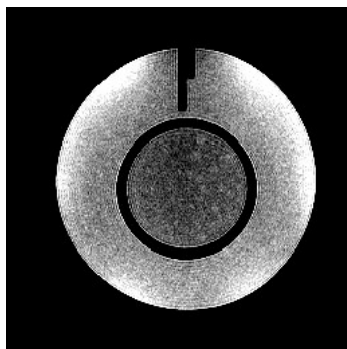
Low Contrast - #8



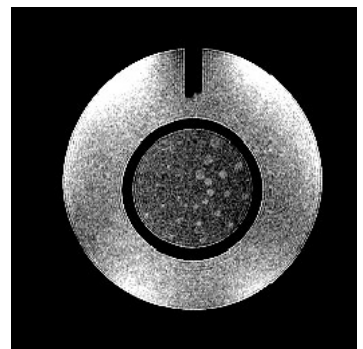
Low Contrast - #9

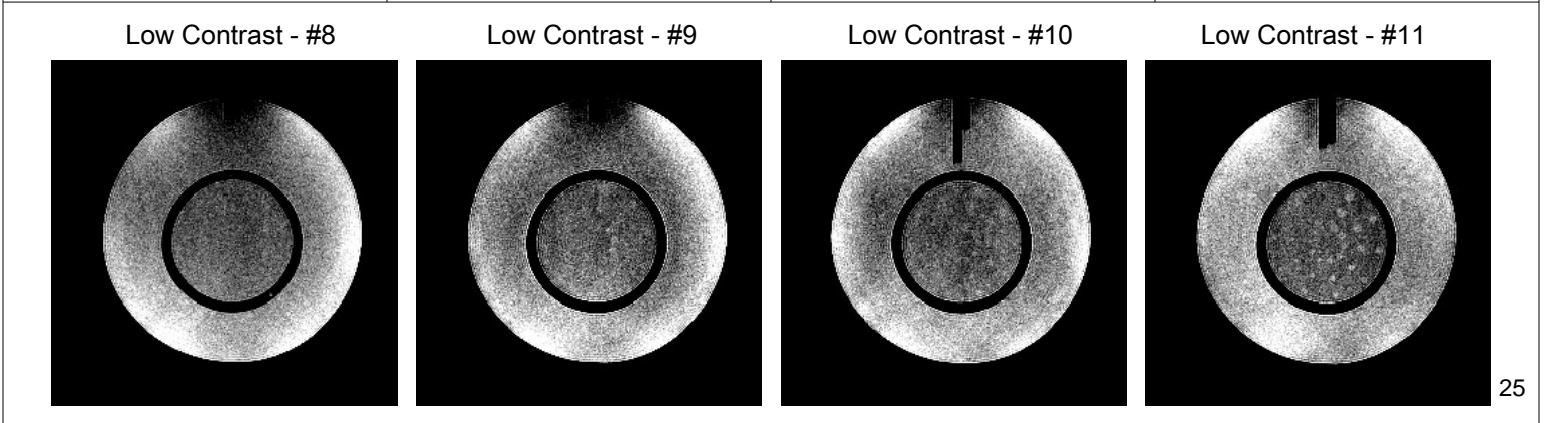
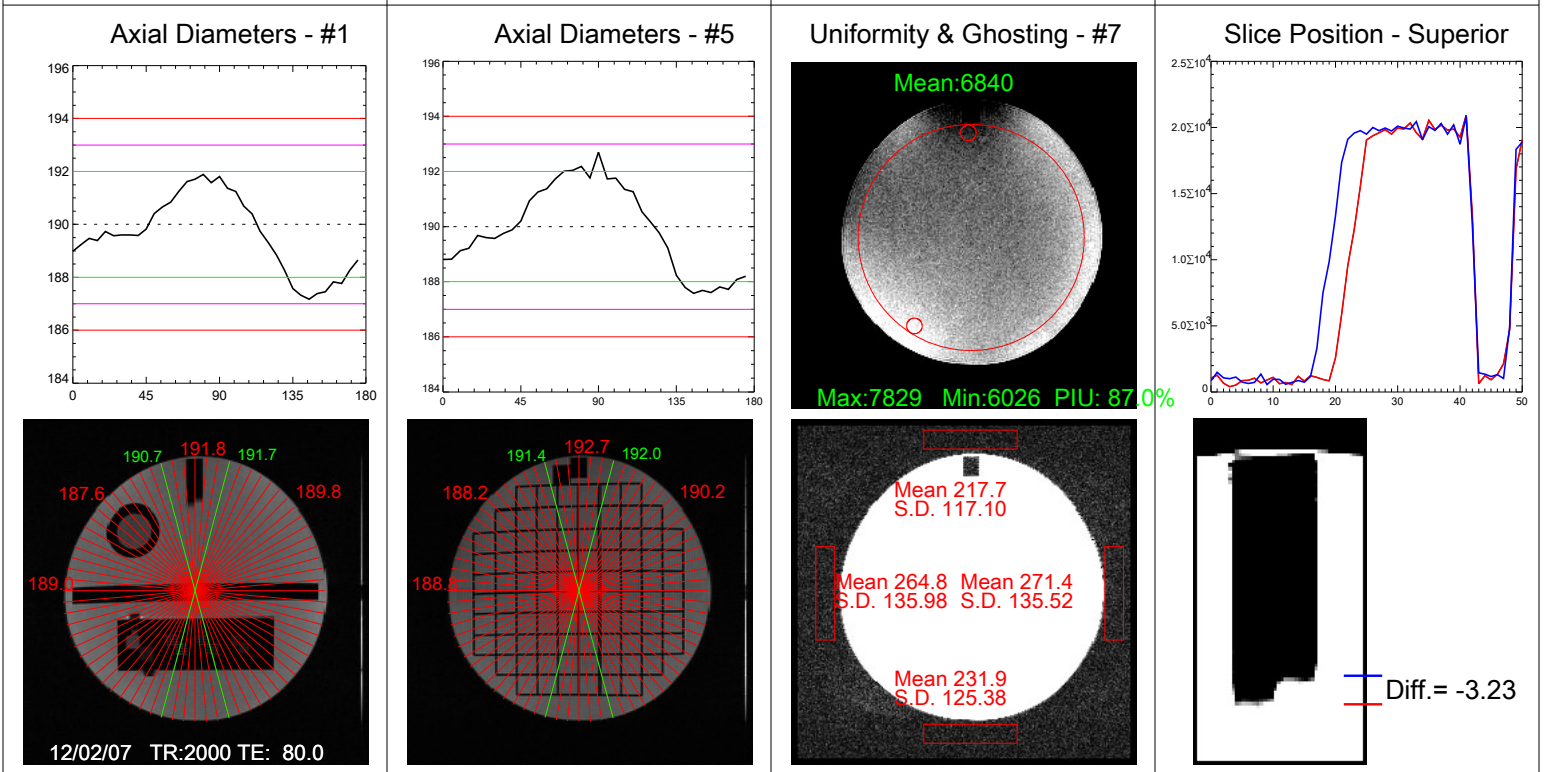
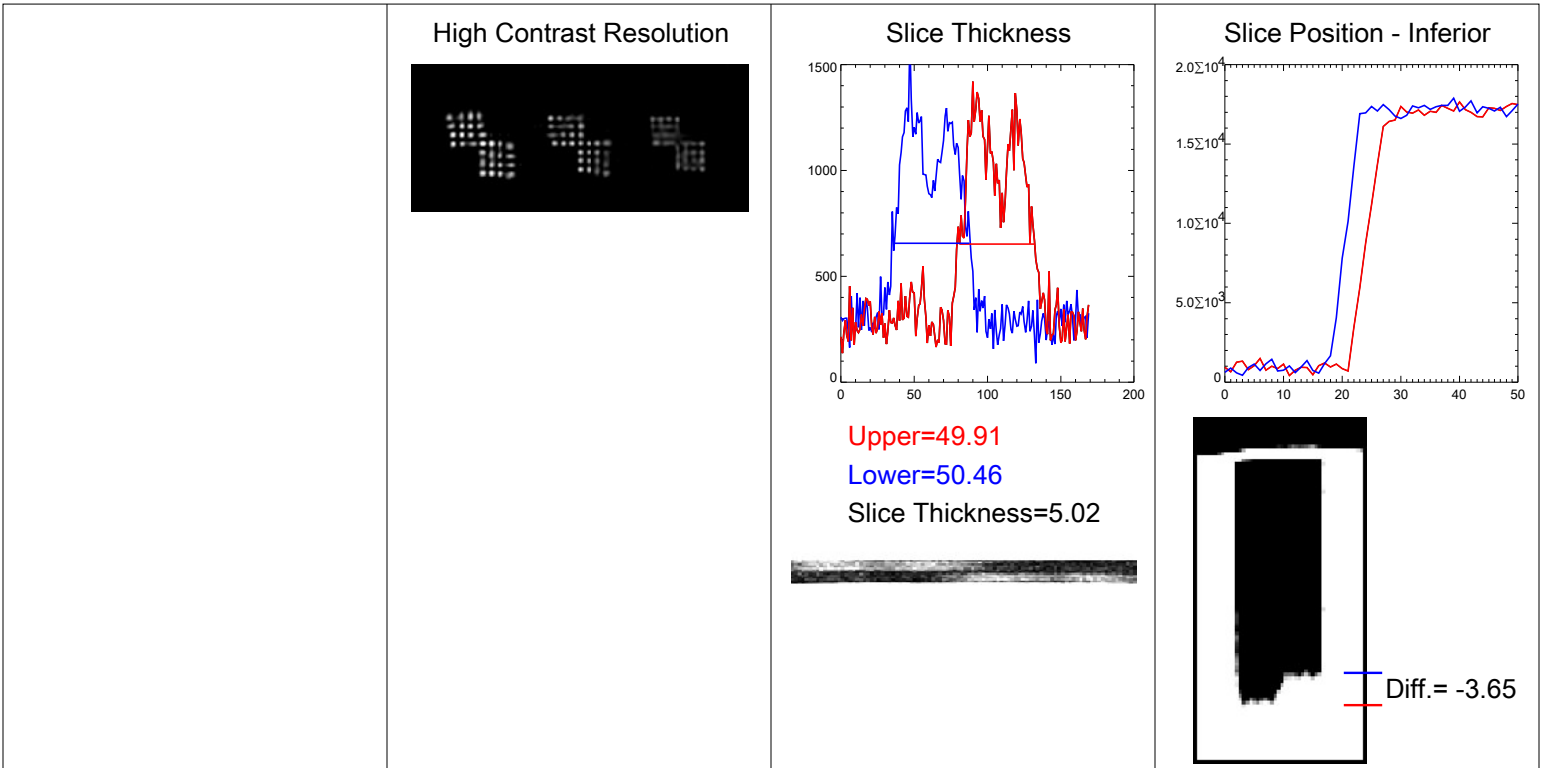


Low Contrast - #10



Low Contrast - #11

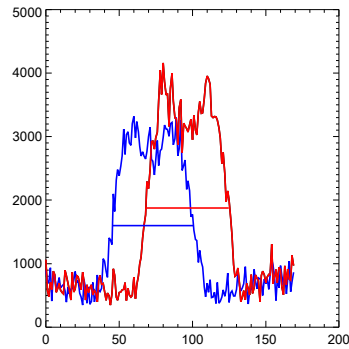




High Contrast Resolution



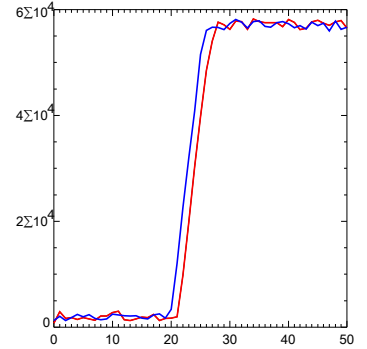
Slice Thickness



Upper=55.26
Lower=54.48
Slice Thickness=5.49

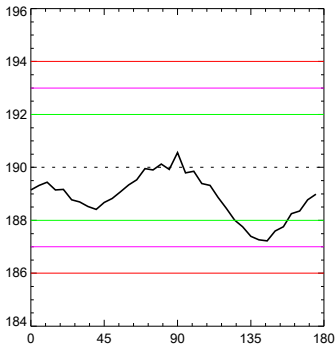


Slice Position - Inferior

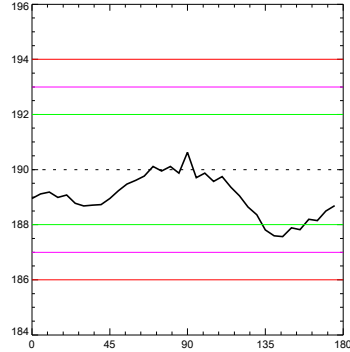


Diff. = -1.20

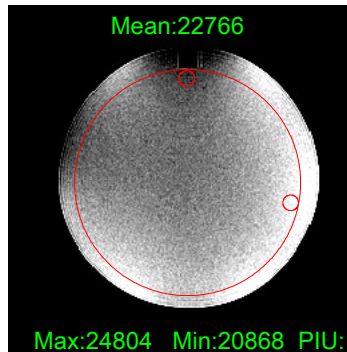
Axial Diameters - #1



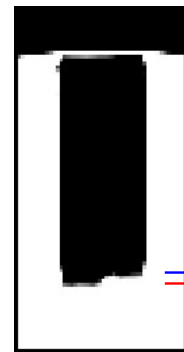
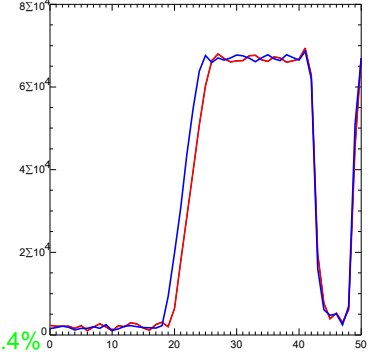
Axial Diameters - #5



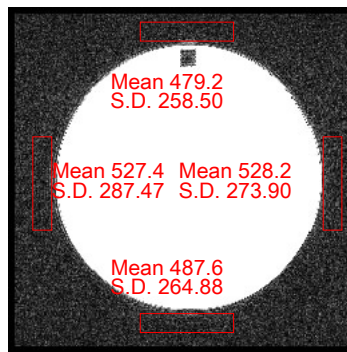
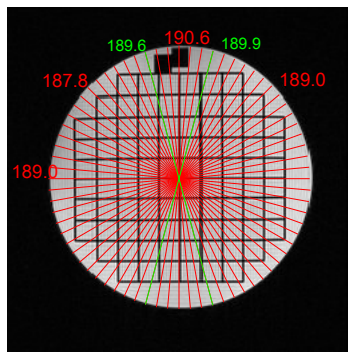
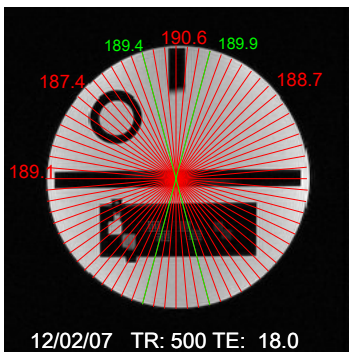
Uniformity & Ghosting - #7



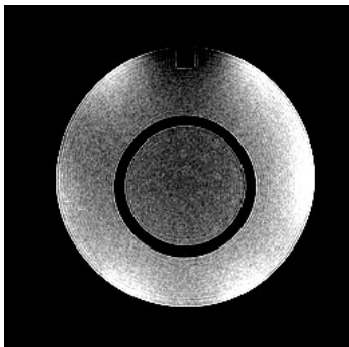
Slice Position - Superior



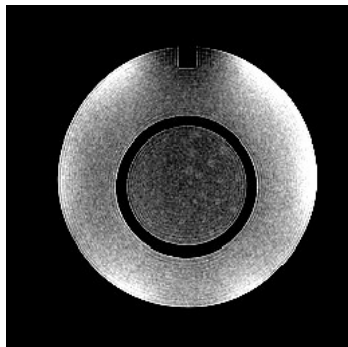
Diff. = -1.26



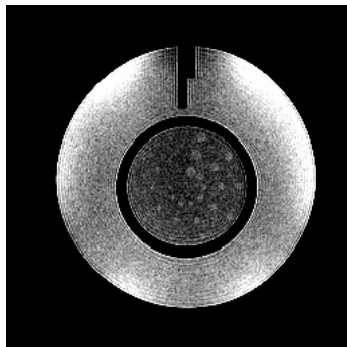
Low Contrast - #8



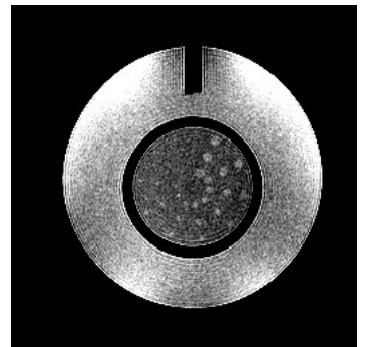
Low Contrast - #9



Low Contrast - #10



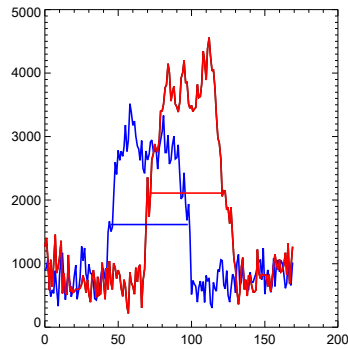
Low Contrast - #11



High Contrast Resolution



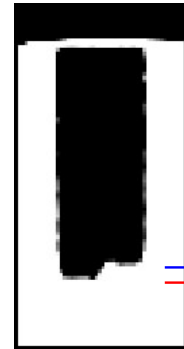
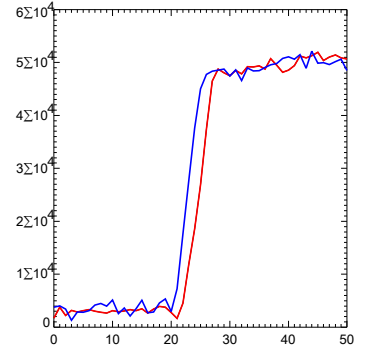
Slice Thickness



Upper=50.11
Lower=51.49
Slice Thickness=5.08

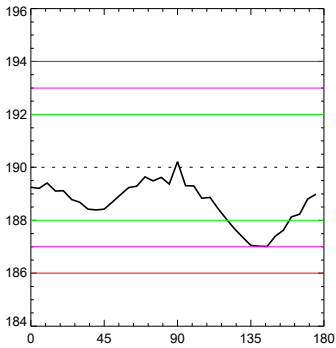


Slice Position - Inferior

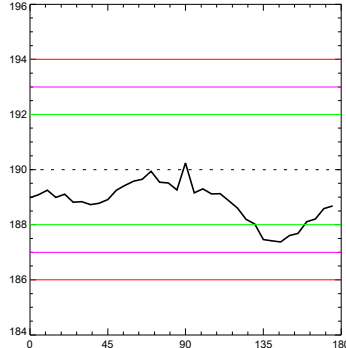


Diff. = -1.73

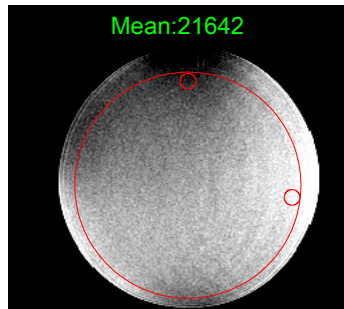
Axial Diameters - #1



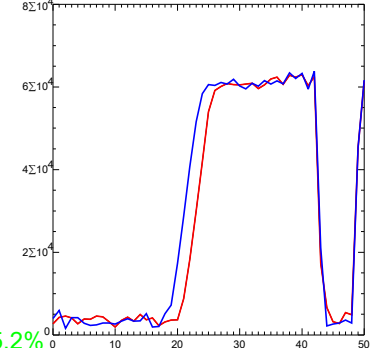
Axial Diameters - #5



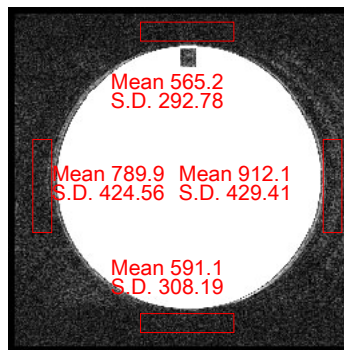
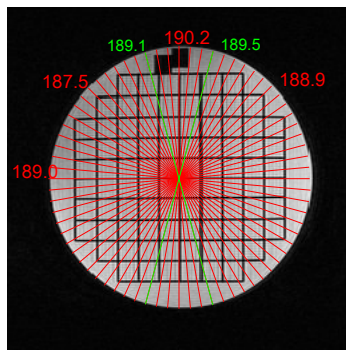
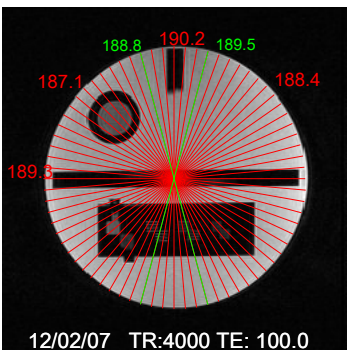
Uniformity & Ghosting - #7



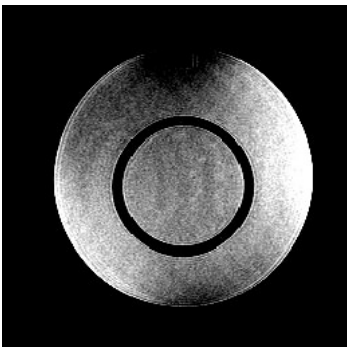
Slice Position - Superior



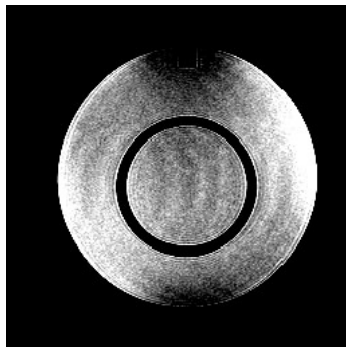
Diff. = -1.90



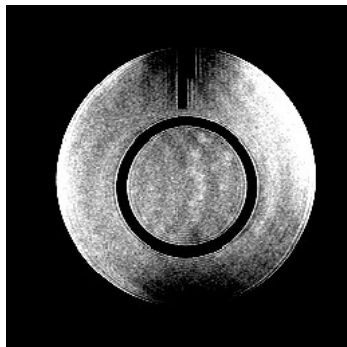
Low Contrast - #8



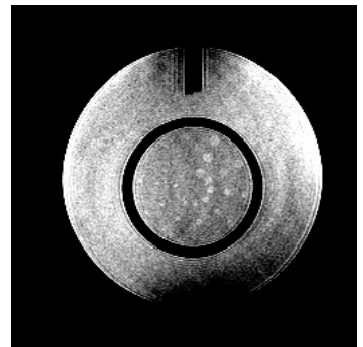
Low Contrast - #9



Low Contrast - #10



Low Contrast - #11



Appendix D: Explanation of RF Coil Testing Report

Introduction

The primary goal of RF coil testing is to establish some sort of base line for tracking coil performance over time. The most common measure is the Signal to Noise Ratio or SNR. In addition, we can look at overall signal uniformity, ghosting level (or better - lack of ghosting) and in the case of phased array coils we look at the SNR of each and every channel and at symmetry between channels. Unfortunately, there is no single best method for measuring SNR. Below I explain the different methods used and the rationale for each.

SNR

One needs to measure the signal in the phantom (either mean or peak or both) and then divide that by the background noise. Measuring the signal is fairly straightforward, the noise can be more problematic. The simplest method is to measure the standard deviation (SD) in the background 'air'. However, MRI images are the magnitude of complex data. The noise in the underlying complex data is Gaussian but it follows a Rician distribution when the magnitude is used. The true noise can be estimated by multiplying the measured SD by 1.526.

During the reconstruction process, most manufacturers perform various additional operations on the images, This could include geometric distortion correction, low pass filtering of the k-space data resulting in low signal at the edge of the images, RF coil intensity correction (PURE, CLEAR, SCIC, etc), and other processing during the combination of phased array data and parallel imaging techniques. All of these methods distort the background noise making it impossible to obtain an accurate (and reproducible) estimate of the image noise in the air region. The alternative is to use a method which I shall refer to as the NEMA (National Electrical Manufacturers Association) method. The signal in the phantom area is a sum of the proton signal and noise. Once the signal to noise ratio exceeds 5:1, the noise in the magnitude image is effectively Gaussian. To eliminate the proton signal, you acquire an image twice and subtract them. The measured SD in the phantom region should now be the true SD times the square root of 2. When determining the SNR using the NEMA method, calculate the mean signal of the average of the two source images then divide by $.7071 \times$ the SD measured in the same area as the mean signal.

Unfortunately, this doesn't always work. It is absolutely imperative that the RF channel scalings, both transmit and receive, be identical with both scans. Any ghosting in the system is not likely to repeat exactly for both scans and will cause a much higher SD. Finally, the phantom needs to be resting in place prior to the scan long enough for motion of the fluid to have died down. Depending on the size and shape of the phantom, this could take anywhere from 5 to 20 minutes.

One of the most common causes of ghosting is vibration from the helium cold-head. The best way to eliminate this artifact is to turn off the cold head, which will increase helium consumption. Because this vibration is periodic, the ghosting is usually of an $N/2$ nature. The affect inside the signal region of the phantom can be minimized by using a FOV that is twice the diameter of the phantom (measured in the PE direction.) If the noise is to be measured in the air, then be sure to NOT make measurements to either side of the phantom in the PE direction.

Scan parameters also significantly affect measured SNR. For most of the testing performed in this document I used a simple Spin Echo with a TR of 300, a TE of 20 and a slice thickness of 3mm and a receiver BW of 15.6 KHz. The FOV was varied depending on the size of the coil and the phantom used. All of the parameters used for each test can be found on each page immediately below the coil description.

Report Layout

Each page of this report lists the data from a single test. The top third of the page describes the coil and phantom information, followed by the scan parameters used. The middle third contains the numbers measured and calculated results. This section will contain one table if the coil being tested is a single channel coil (i.e. quadrature or surface coils) and two tables if it is a multi-channel phased array coil. The entries in the table will be described further below. The bottom section contains a few lines of comments (if necessary), a picture of the coil with the phantom as used for the testing and one or more of the images that were used for the measurements.

There is usually one image for each composite image measurement and one image for each separate channel measurement. Each image shows the ROI (red line) where the mean signal was measured and two smaller ROIs (green lines) where the signal minimum and maximum was found. In the top left corner of each image is the mean signal in the large ROI. The bottom left corner contains the large ROI's area (in mm²). The top right corner contains two numbers a mean and a standard deviation. If the NEMA method was used, then the top right corner will list the mean and SD of the large ROI (labeled ROI M and ROI_{sd}) applied to the subtraction image. If the noise was measured in the background air the the numbers are labeled Air M and AirSD.

Data Tables

The meaning of most of the entries in the data table are should be self evident with a few exceptions. The first column in each table is labeled "Label". In the composite analysis, this field may be empty or contain some sort of abbreviation to identify some aspect of the testing. Some possibilities are the letter N for NEMA, A for Air, L for Left, R for Right, C for CLEAR, NoC for No CLEAR. In the Uncombined Image table, the label usually contains the channel number or similar descriptor. The column labeled "Noise Type" will be either Air or SubSig which stands for Subtracted Signal, *i.e.* the NEMA method. Both tables contain a column for Mean SNR and Max SNR which are the Mean or Max signal divided by the SD of the noise scaled by either 1.526 (Air) or 0.7071 (NEMA).

Composite Image Table: The final two columns in this table are "Normalized" and "Uniformity". It can be rather difficult to compare the performance of different coils particularly if different scan parameters are used. (Of course, it's even more difficult from one scanner to another.) I have standardized most of my testing to use a spin echo with a TR/TE of 300/20msec and a thickness of 3 mm. The FOV changes to depending on the size of the phantom used although I try to use a FOV that is at least twice the diameter of the phantom as measured in the PE direction. For one reason or another, a change may be made in the scan parameters (either accidentally or intentionally such as turning on No Phase Wrap to eliminate aliasing, etc.). In order to make it easier to compare SNR values I calculate a "Normalized" SNR value. This value is theoretically what the SNR would be if a FOV of 30cm, 256x256 matrix, 1 average, receiver BW of 15.6 KHz and slice thickness of 3mm had been used. Obviously, the final number is affected by the T1/T2 values of the phantoms used as well as details of the coil and magnet field strength but it can be useful in certain situations.

The "Uniformity" value is defined by the ACR as $1 - (\max - \min) / (\max + \min)$. This is most important when looking at volume coils or for evaluating the effectiveness of surface coil intensity correction algorithms (such as PURE, CLEAR or SCIC).

Uncombined Image Table: This table has two columns labeled "% of Mean" and "% of Max". When analyzing multi-channel coils it is important to understand the relationship between the different channels, the inherent symmetry that usually exists between channels. In a 8 channel head or 4 channel torso phased array coil, all of the channels are usually have about the same SNR. These two columns list how the SNR (either Mean or Max) of each channel compares to the SNR of the channel with the maximum value.